

Programming unitary operators in a linear-algebraic typed lambda-calculus

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Aim of the work

- Present the semantics of a **linear algebraic lambda-calculus** based on a realizability model that captures a notion of unitarity (ℓ_2 -norm)
 - **lambda-calculus** = functional programming (see next slides)
 - **algebraic** = linear combinations of terms (to represent superpositions of values / superpositions of programs)
 - **linear** = all functions are linear by construction
- **Main novelty:** The calculus is designed from a **realizability model** (a notion coming from logic, Kleene 1945)
- A language to represent:
 - classical values, classical programs
 - superposition of values, superposition of programs
 - classical programs computing superposition of values
 - superposition of programs computing superposition of values
- A semantics for **quantum programming languages** (Quipper)

Plan

- 1 Introduction
- 2 The lambda-calculus
- 3 Adding linear combinations
- 4 A unitary linear-algebraic lambda-calculus

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The pure λ -calculus

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- Introduced by Alonzo Church (1903–1995) in the 1930s
... to solve Hilbert's *Entscheidungsproblem* (Decision problem)
- Minimal functional programming language. Only:
 - 3 syntactic constructs (variable, λ -abstraction, application)
 - 1 computation rule (β -reduction)
- Actually, the **first programming language ever!** ...
... if we do not count Charles Babbage's (partial) attempt
- Same computation strength as Turing machines
Turing (1912-1954), who had invented his abstract machines independently, became Church's PhD student in Princeton
- The λ -calculus is now the core of all functional programming languages: Lisp, Scheme, Erlang, OCaml, Haskell, F#, etc.

Adding types

- To avoid undesirable phenomena (self-application, non termination, etc.) it is natural to only consider **well-typed λ -terms**
- A possible algebra of types (notation: A, B, C , etc.) is:

$$A, B, C ::= \mathbb{U} \mid A \rightarrow B \mid A \times B \mid A + B$$

\mathbb{U} is the **unit type**, from which we can form the **type of Booleans** $\mathbb{B} := \mathbb{U} + \mathbb{U}$

- Well-typedness of terms is enforced using a **typing judgment**

$$\Gamma \vdash t : A \quad (\text{"in context } \Gamma, t \text{ has type } A")$$

where

- Γ is a **typing context**, of the form $\Gamma \equiv x_1 : A_1, \dots, x_n : A_n$
- t is a term (possibly depending on x_1, \dots, x_n)
- A is a type

The function type $A \rightarrow B$

- $A \rightarrow B$ is the type of functions from A to B

Construction: $\lambda x. s$ (λ -abstraction)

Destruction: $t u$ (application)

- Computation:

$(\lambda x. s) u \rightsquigarrow s[x := u]$ (β -reduction)

- Typing rules:

$$\frac{\Gamma, x : A \vdash s : B}{\Gamma \vdash \lambda x. s : A \rightarrow B}$$

$$\frac{\Gamma \vdash t : A \rightarrow B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B}$$

The Cartesian product $A \times B$

- $A \times B$ is the type of pairs (u, v) , where $u : A$ and $v : B$

Construction: (u, v) (ordered pair)

Destruction: $\text{let } (x, y) = t \text{ in } s$ (“let” for pairs)

- Computation:

$$\text{let } (x, y) = (u, v) \text{ in } s \rightsquigarrow s[x := u, y := v]$$

- Typing rules:

$$\frac{\Gamma \vdash u : A \quad \Gamma \vdash v : B}{\Gamma \vdash (u, v) : A \times B}$$

$$\frac{\Gamma \vdash t : A \times B \quad \Gamma, x : A, y : B \vdash s : C}{\Gamma \vdash \text{let } (x, y) = t \text{ in } s : C}$$

The direct sum $A + B$

- $A + B$ is the direct sum (disjoint union) of types A and B

Construction: $\text{inl}(u), \text{inr}(v)$

Destruction: $\text{match } t \{ \text{inl}(x) \mapsto s_1 \mid \text{inr}(y) \mapsto s_2 \}$

- Computation:

$$\text{match } \text{inl}(u) \{ \text{inl}(x) \mapsto s_1 \mid \text{inr}(y) \mapsto s_2 \} \rightsquigarrow s_1[x := u]$$

$$\text{match } \text{inr}(v) \{ \text{inl}(x) \mapsto s_1 \mid \text{inr}(y) \mapsto s_2 \} \rightsquigarrow s_2[y := v]$$

- Typing rules:

$$\frac{\Gamma \vdash u : A}{\Gamma \vdash \text{inl}(u) : A + B}$$

$$\frac{\Gamma \vdash v : B}{\Gamma \vdash \text{inr}(v) : A + B}$$

$$\frac{\Gamma \vdash t : A + B \quad \Gamma, x : A \vdash s_1 : C \quad \Gamma, y : B \vdash s_2 : C}{\Gamma \vdash \text{match } t \{ \text{inl}(x) \mapsto s_1 \mid \text{inr}(y) \mapsto s_2 \} : C}$$

The unit type \mathbb{U}

- \mathbb{U} is the singleton type (inhabited by a dummy value)

Construction: $*$ (dummy value)

Destruction: $t; s$ (sequence)

- Computation: $*; s \rightsquigarrow s$

- Typing rules:

$$\frac{}{\Gamma \vdash * : \mathbb{U}} \quad \frac{\Gamma \vdash t : \mathbb{U} \quad \Gamma \vdash s : C}{\Gamma \vdash t; s : C}$$

- Combining \mathbb{U} with $+$, we define the type of Booleans:

$\mathbb{B} := \mathbb{U} + \mathbb{U}$

$\mathbf{tt} := \mathbf{inl}(*)$

$\mathbf{ff} := \mathbf{inr}(*)$

$\mathbf{if } t \{s_1 \mid s_2\} := \mathbf{match } t \{ \mathbf{inl}(x) \mapsto x; s_1 \mid \mathbf{inr}(y) \mapsto y; s_2 \}$

The simply-typed λ -calculus

- Equipped with a **type system** such as the one presented above, the λ -calculus enjoys excellent properties:
 - Computation is ultimately deterministic: the computed value does not depend on evaluation strategy (already holds in the untyped case)
 - Types are preserved throughout computations
 - All well-typed computations **terminate**
- The simply-typed λ -calculus has also good semantics:
 - set-theoretic semantics, denotational semantics, categorical semantics, **realizability semantics** (cf later)
- Strong relationship with logic:

The Curry-Howard correspondence

t is a **program of type** A \equiv t is a **proof of formula** A

$A \rightarrow B, A \times B, A + B \equiv A \Rightarrow B, A \wedge B, A \vee B$

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Aim of the calculus

- **Intuitions:** Terms of the simply-typed λ -calculus represent **classical programs** computing **classical values**
- We now want to represent
 - superposition of values
 - classical programs computing superposition of values
 - superposition of programs computing superposition of values
- For that, we extend the λ -calculus with **linear combinations**

$$s, t ::= x \mid \lambda x . t \mid s t \mid \dots \mid \vec{0} \mid t + u \mid \alpha \cdot t$$

- Beware!

$$\lambda x . \left(\frac{1}{\sqrt{2}} \cdot \mathbf{tt} + \frac{1}{\sqrt{2}} \cdot \mathbf{ff} \right) \neq \frac{1}{\sqrt{2}} \cdot (\lambda x . \mathbf{tt}) + \frac{1}{\sqrt{2}} \cdot (\lambda x . \mathbf{ff})$$

- We also would like the type system to capture **unitary operators** (in an infinite dimensional space of values)

Linear combinations and non termination

- **Problem:** Linear combinations badly interact with non termination

$$\text{Let: } Y_t := (\lambda x . t + xx)(\lambda x . t + xx) \quad (t \text{ fixed term})$$

$$\not\approx t + Y_t$$

$$\text{Hence: } \vec{0} = Y_t - Y_t \not\approx (t + Y_t) - Y_t = t + \vec{0} = t$$

⇒ Confluence is lost! (on untyped terms)

- Several solutions have been considered to fix this problem:
 - Restricting the rules of evaluation [Arrighi & Dowek '08, '17]
 - Working with positive coefficients only [Vaux '09]
 - Restricting to well-typed terms [Arrighi & Díaz-Caro '11, '12]
 - Working with **weak linear combinations** [Valiron '13]

Weak vector spaces

(1/2)

Definition (Weak vector space)

[Valiron '13]

A **weak \mathbb{C} -vector space** is a commutative monoid $(V, +, \vec{0})$ equipped with a scalar multiplication $(\cdot) : \mathbb{C} \times V \rightarrow V$ such that

$$\begin{array}{ll} 1 \cdot u = u & (\alpha + \beta) \cdot u = \alpha \cdot u + \beta \cdot u \\ \alpha \cdot (\beta \cdot u) = \alpha\beta \cdot u & \alpha \cdot (u + v) = \alpha \cdot u + \alpha \cdot v \end{array}$$

for all $u, v \in V, \alpha, \beta \in \mathbb{C}$

- **Intuition:** Weak vector space = vector space whose additive structure is **not an abelian group**, but a **commutative monoid**
 \Rightarrow vectors do not have an opposite, in general
- In a weak vector space:

$$\alpha \cdot \vec{0} = \vec{0}, \quad \text{but} \quad 0 \cdot u \neq \vec{0} \quad \text{and} \quad (-1) \cdot u \neq -u$$

Note that $(-1) \cdot u + u = (-1) \cdot u + 1 \cdot u = (-1 + 1) \cdot u = 0 \cdot u \neq \vec{0}$

Weak vector spaces

(2/2)

- Weak vector spaces already occur in mathematics!

Observation: If V and W are (ordinary) \mathbb{C} -vector spaces, then the set of all **unbounded operators** from V to W is a weak \mathbb{C} -vector space

- The category of weak vector spaces has excellent properties:
 - It has all limits and all colimits (it is bicomplete)
 - It is monoidal closed ($\otimes \dashv \multimap$)
 - It has all **free objects**: weak linear combinations, a.k.a. **distributions**
(In a distribution, summands of the form $0 \cdot u$ do not cancel)
- We should not think of algebraic programs as bounded operators, not even as totally defined operators, but as **abstract unbounded operators** (neither total nor continuous)

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Syntax of the calculus

Pure values	$v, w ::= x \mid \lambda x. \vec{s} \mid *$ $\mid (v, w) \mid \text{inl}(v) \mid \text{inr}(v)$
Pure terms	$s, t ::= v \mid s t \mid t; \vec{s}$ $\mid \text{let } (x_1, x_2) = t \text{ in } \vec{s}$ $\mid \text{match } t \{ \text{inl}(x_1) \mapsto \vec{s}_1 \mid \text{inr}(x_2) \mapsto \vec{s}_2 \}$
Value distr.	$\vec{v}, \vec{w} ::= \vec{0} \mid v \mid \vec{v} + \vec{w} \mid \alpha \cdot \vec{v} \quad (\alpha \in \mathbb{C})$
Term distr.	$\vec{s}, \vec{t} ::= \vec{0} \mid t \mid \vec{s} + \vec{t} \mid \alpha \cdot \vec{t} \quad (\alpha \in \mathbb{C})$

- Term/value distributions are endowed with the equational theory of **distributions** (summands of the form $0 \cdot t$ do not cancel)
- Syntactic constructs are extended by linearity:

$(\vec{v}, \vec{w}), \quad \vec{s} \vec{t}$ are bilinear
 $\text{inl}(\vec{v}), \quad \text{inl}(\vec{v})$ are linear in \vec{v}
 $\vec{t}; \vec{s}, \quad \text{let } (x, y) = \vec{t} \text{ in } \vec{s},$
 $\text{match } \vec{t} \{ \text{inl}(x) \mapsto \vec{s}_1 \mid \text{inr}(y) \mapsto \vec{s}_2 \}$ are linear in \vec{t}

Evaluation

- Evaluation is defined from the 'atomic' rules

$$\begin{array}{lcl}
 (\lambda x. \vec{t}) v & \rightsquigarrow & \vec{t}[x := v] \\
 *; \vec{s} & \rightsquigarrow & \vec{s} \\
 \text{let } (x, y) = (v, w) \text{ in } \vec{s} & \rightsquigarrow & \vec{s}[x := v, y := w] \\
 \text{match inl}(v) \{ \text{inl}(x) \mapsto \vec{s}_1 \mid \text{inr}(y) \mapsto \vec{s}_2 \} & \rightsquigarrow & \vec{s}_1[x := v] \\
 \text{match inr}(v) \{ \text{inl}(x) \mapsto \vec{s}_1 \mid \text{inr}(y) \mapsto \vec{s}_2 \} & \rightsquigarrow & \vec{s}_2[y := v]
 \end{array}$$

and then extended by linearity (as a relation)

- Call-by-basis** strategy = call-by-value + all functions are linear

$$\begin{aligned}
 (\lambda x. \vec{s}) \vec{t} & \rightsquigarrow (\lambda x. \vec{s}) \left(\sum_j \beta_j \cdot v_j \right) & = & \sum_j \beta_j \cdot (\lambda x. \vec{s}) v_j \\
 & & & \rightsquigarrow \sum_j \beta_j \cdot \vec{s}[x := v_j]
 \end{aligned}$$

Theorem: Evaluation is confluent

(on untyped terms)

Note: Only holds because we are using distributions (= weak linear combinations)

The realizability model

- The weak vector space \vec{V} of closed value distributions is equipped with the scalar product $\langle \vec{v} \mid \vec{w} \rangle$ and the ℓ_2 -seminorm $\|\vec{v}\|$
- All constructions are performed in the **unit sphere** $\mathcal{S}_1 \subseteq \vec{V}$

Definition (Types)

A **type** is a notation A together with a set of unit vectors $\llbracket A \rrbracket \subseteq \mathcal{S}_1$

• Examples:

- The type \mathbb{B} (of Booleans) is defined by $\llbracket \mathbb{B} \rrbracket := \{\mathbf{tt}, \mathbf{ff}\}$
- To each type A , we associate the type $\sharp A$ (**unitary span** of A) that is defined by $\llbracket \sharp A \rrbracket := \text{span}(\llbracket A \rrbracket) \cap \mathcal{S}_1$
- So that we can form the type $\sharp \mathbb{B}$ (of **unitary Booleans**)
- To each type A , we associate the **realizability predicate**

$$\vec{t} \Vdash A \quad \equiv \quad \exists \vec{v} \in \llbracket A \rrbracket, \vec{t} \succcurlyeq \vec{v}$$

(\vec{t} evaluates to a value distribution of type A)

A simple algebra of types

(2/2)

Types $A, B ::= \mathbb{U} \mid \flat A \mid \sharp A \mid A \times B$
 $\mid A + B \mid A \rightarrow B \mid A \Rightarrow B$

Abbrev.: $\mathbb{B} := \mathbb{U} + \mathbb{U}, \quad A \otimes B := \sharp(A \times B), \quad A \oplus B := \sharp(A + B)$

- The **direct sum** $A + B$ of two types A and B is defined by

$$\llbracket A + B \rrbracket := \{ \text{inl}(\vec{v}) : \vec{v} \in \llbracket A \rrbracket \} \cup \{ \text{inr}(\vec{w}) : \vec{w} \in \llbracket B \rrbracket \}$$

- The **pure function space** $A \rightarrow B$ from A to B is defined by:

$$\llbracket A \rightarrow B \rrbracket := \{ \lambda x. \vec{t} : \forall \vec{v} \in \llbracket A \rrbracket, \vec{t} \langle x := \vec{v} \rangle \Vdash B \}$$

- The **unitary function space** $A \Rightarrow B$ from A to B is defined by:

$$\llbracket A \Rightarrow B \rrbracket := \left\{ \left(\sum_{i=1}^n \alpha_i \cdot \lambda x. \vec{t}_i \right) \in \mathcal{S}_1 : \right. \\ \left. \forall \vec{v} \in \llbracket A \rrbracket, \left(\sum_{i=1}^n \alpha_i \cdot \vec{t}_i \langle x := \vec{v} \rangle \right) \Vdash B \right\}$$

Properties of the semantic type system

- Recall that: $\vec{t} \Vdash A \quad :\equiv \quad \exists \vec{v} \in \llbracket A \rrbracket, \vec{t} \not\approx \vec{v}$

Theorem (Representation of unitary functions)

Let \vec{t} be a program distribution

- $\vec{t} \Vdash \#B \rightarrow \#B$ iff t computes a pure function that represents a unitary operator from \mathbb{C}^2 to \mathbb{C}^2
- $\vec{t} \Vdash \#B \Rightarrow \#B$ iff t computes a unitary function distribution that represents a unitary operator from \mathbb{C}^2 to \mathbb{C}^2

- From the realizability relation, we extract a **type system** based on typing rules that are correct w.r.t. the semantics
- This system is an extension of the simply-typed λ -calculus (that now represents the classical part of the language)
- Moreover, the new type constructs ($\flat A$, $\#A$, etc.) allow to capture linearity constraints, and in particular: unitary functions

A possible type system

$$\begin{array}{c}
 \frac{}{x : A \vdash x : A} \text{ (Axiom)} \qquad \frac{\Gamma \vdash \vec{t} : A \quad A \leq A'}{\Gamma \vdash \vec{t} : A'} \text{ (Sub)} \\
 \\
 \frac{\Gamma, x : A \vdash \vec{t} : B \quad b \Gamma \simeq \Gamma}{\Gamma \vdash \lambda x. \vec{t} : A \rightarrow B} \text{ (PureLam)} \qquad \frac{\Gamma, x : A \vdash \vec{t} : B}{\Gamma \vdash \lambda x. \vec{t} : A \Rightarrow B} \text{ (UnitLam)} \\
 \\
 \frac{\Gamma \vdash \vec{s} : A \Rightarrow B \quad \Delta \vdash \vec{t} : A}{\Gamma, \Delta \vdash \vec{s} \vec{t} : B} \text{ (App)} \\
 \\
 \frac{}{\vdash * : \mathbb{U}} \text{ (Void)} \qquad \frac{\Gamma \vdash \vec{t} : \mathbb{U} \quad \Delta \vdash \vec{s} : A}{\Gamma, \Delta \vdash \vec{t}; \vec{s} : A} \text{ (Seq)} \qquad \frac{\Gamma \vdash \vec{t} : \#\mathbb{U} \quad \Delta \vdash \vec{s} : \#A}{\Gamma, \Delta \vdash \vec{t}; \vec{s} : \#A} \text{ (SeqSharp)} \\
 \\
 \frac{\Gamma \vdash \vec{v} : A \quad \Delta \vdash \vec{w} : B}{\Gamma, \Delta \vdash (\vec{v}, \vec{w}) : A \times B} \text{ (Pair)} \qquad \frac{\Gamma \vdash \vec{t} : A \times B \quad \Delta, x : A, y : B \vdash \vec{s} : C}{\Gamma, \Delta \vdash \text{let } (x, y) = \vec{t} \text{ in } \vec{s} : C} \text{ (LetPair)} \\
 \\
 \frac{\Gamma \vdash \vec{t} : A \otimes B \quad \Delta, x : \#A, y : \#B \vdash \vec{s} : \#C}{\Gamma, \Delta \vdash \text{let } (x, y) = \vec{t} \text{ in } \vec{s} : \#C} \text{ (LetTens)} \\
 \\
 \frac{\Gamma \vdash \vec{t} : B \quad b A \simeq A}{\Gamma, x : A \vdash \vec{t} : B} \text{ (Weak)} \qquad \frac{\Gamma, x : A, y : A \vdash \vec{t} : B \quad b A \simeq A}{\Gamma, x : A \vdash \vec{t}[y := x] : B} \text{ (Contr)}
 \end{array}$$

+ many other typing rules / subtyping rules